

Lecture 3: Review of Signal Analysis Basics

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EE421: Communications I

Exponential/Trigonometric/Compact

$$x(t) = \sum_{n=-\infty}^{\infty} \alpha_n \cdot e^{jn\omega_0 t}, \quad \omega_0 = \frac{2\pi}{T}$$

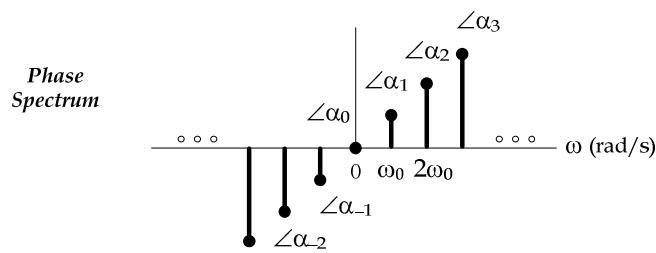
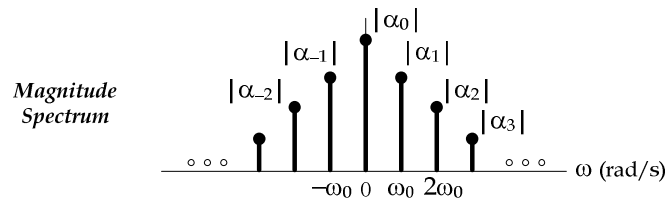
$$x(t) = \frac{a_0}{2} + \sum_{n=1}^{\infty} (a_n \cos(n\omega_0 t) + b_n \sin(n\omega_0 t)), \quad \omega_0 = \frac{2\pi}{T}$$

$$x(t) = \frac{c_0}{2} + \sum_{n=1}^{\infty} c_n \cos(n\omega_0 t - \theta_n), \quad \omega_0 = \frac{2\pi}{T}$$

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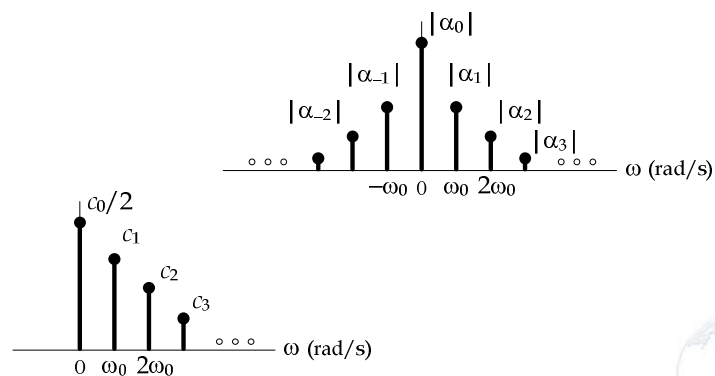
Exponential Fourier Series



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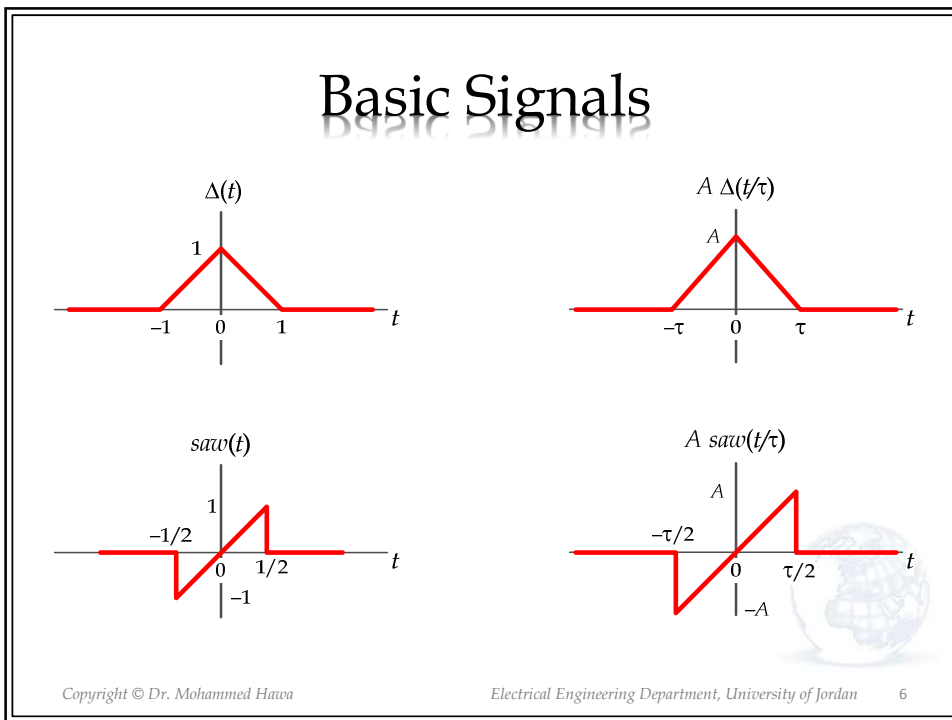
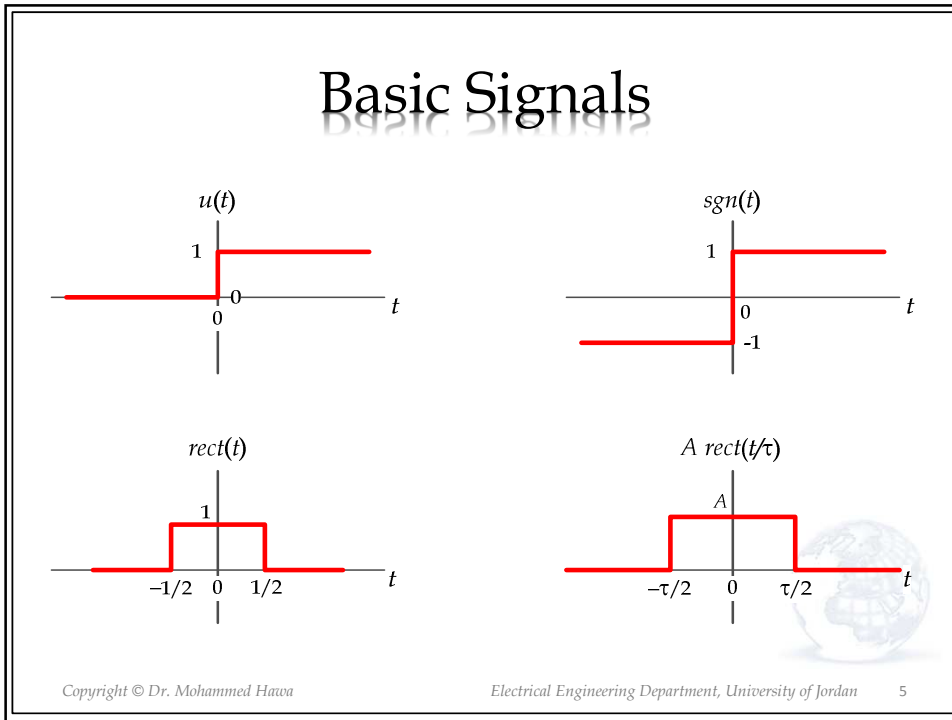
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Single-Sided vs. Double-Sided

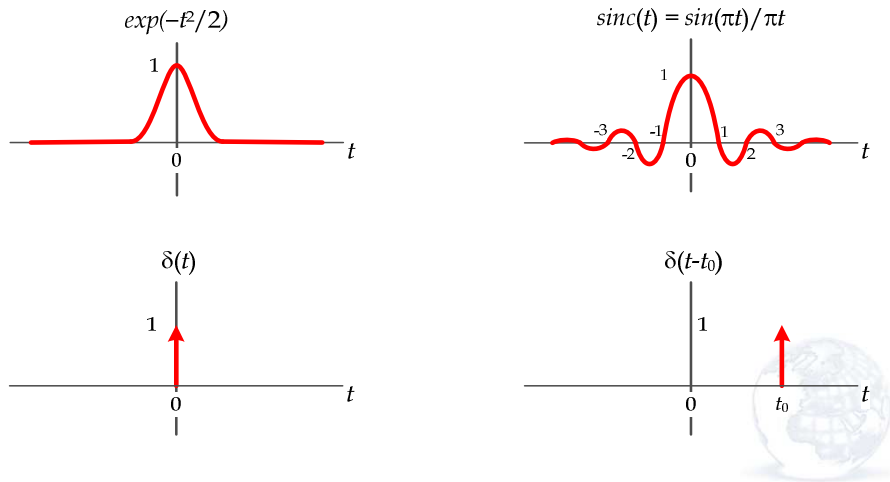


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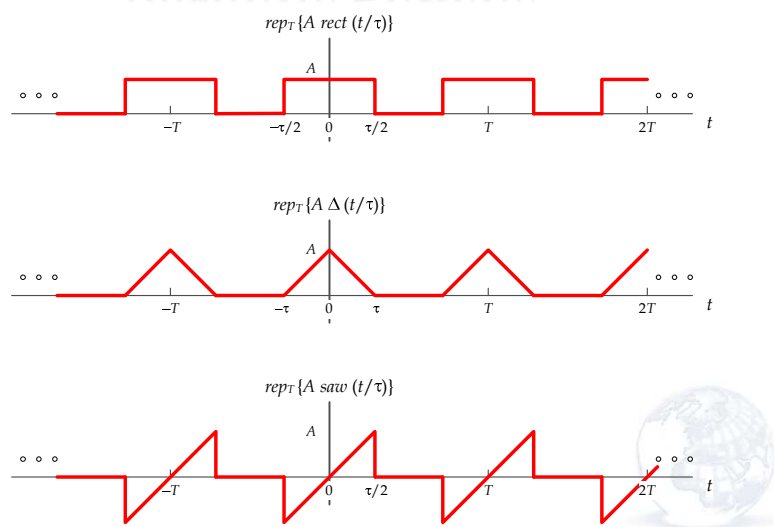
Basic Signals



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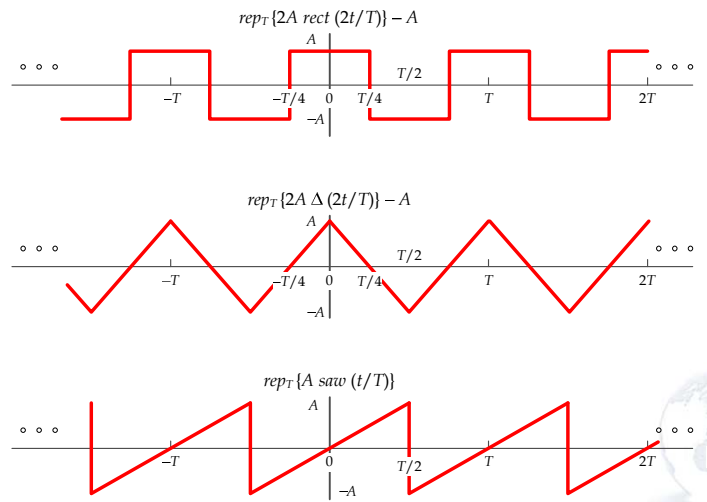
Periodic Signals



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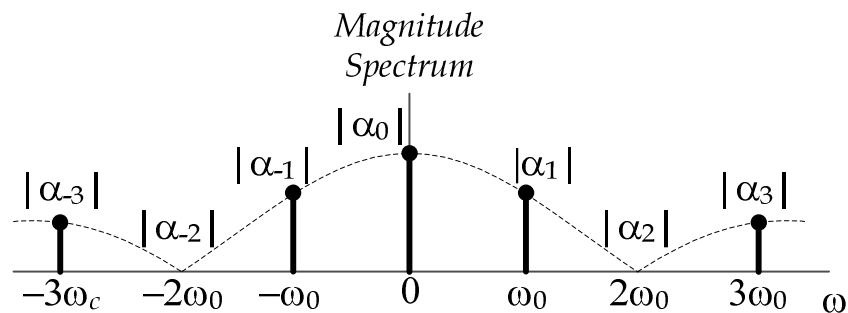
Periodic Signals



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First-Null Bandwidth



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Fourier Transform

$$X(\omega) = \mathcal{F}\{x(t)\} = \int_{-\infty}^{\infty} x(t)e^{-j\omega t} dt$$

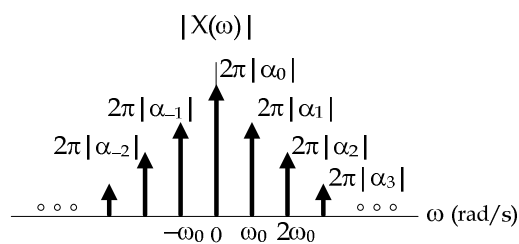
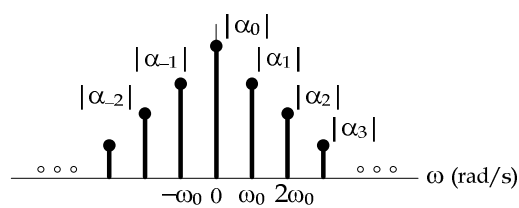
$$x(t) = \mathcal{F}^{-1}\{X(\omega)\} = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega)e^{j\omega t} d\omega$$



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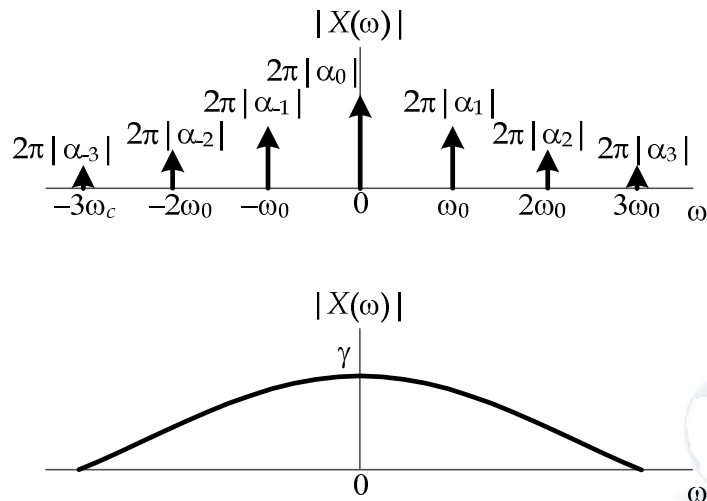
Fourier Series vs. Transform



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Periodic vs. Aperiodic



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DC vs. Average Power

The DC value or average value of the signal $x(t)$ is:

$$DC = \overline{x(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x(t) dt$$

$$DC = \overline{x(t)} = \alpha_0$$

The average power in the signal $x(t)$ is:

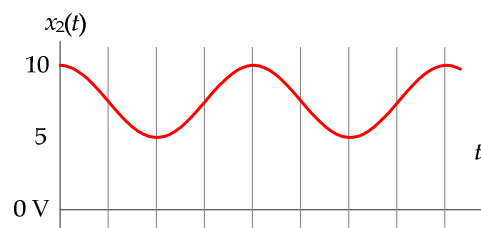
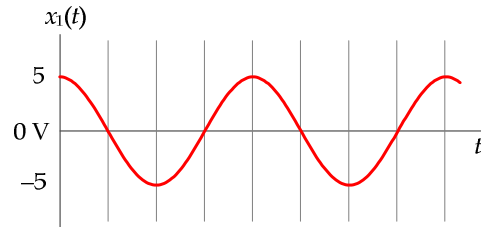
$$P_x = \overline{x^2(t)} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$$

$$P_x = \overline{x^2(t)} = \frac{1}{2\pi} \int_{-\infty}^{\infty} S_x(\omega) d\omega$$

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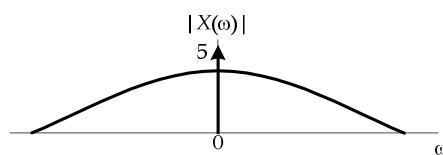
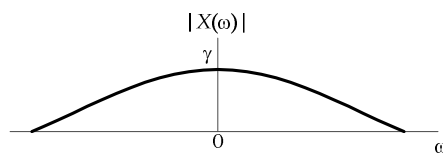
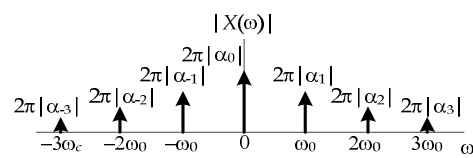
DC vs. Average Power



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DC from Frequency Domain

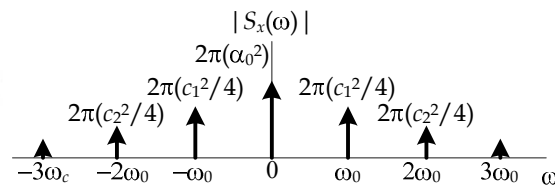
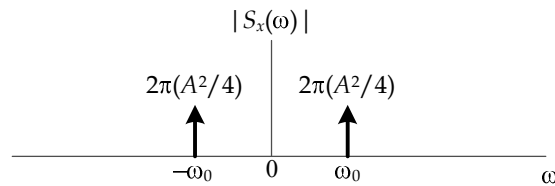


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Power Spectral Density

$$\text{PSD} = S_x(\omega) = \lim_{T \rightarrow \infty} \frac{1}{T} |X_T(\omega)|^2 = \mathcal{F}\{R_{xx}(\tau)\}$$



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Quick Review of Filters

- There are four main filter types that you studied in signal analysis:
 - **LPF: Low-Pass Filter**
 - **BPF: Band-Pass Filter**
 - **HPF: High-Pass Filter**
 - **Band-Stop Filter / Notch Filter.**

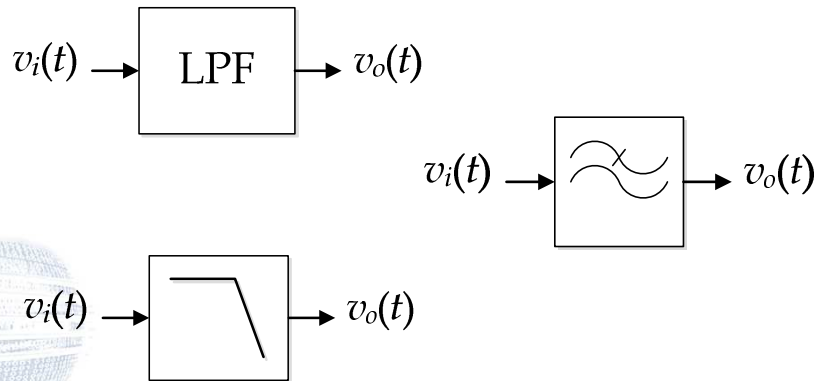


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Low-Pass Filter (LPF)

- Symbol:

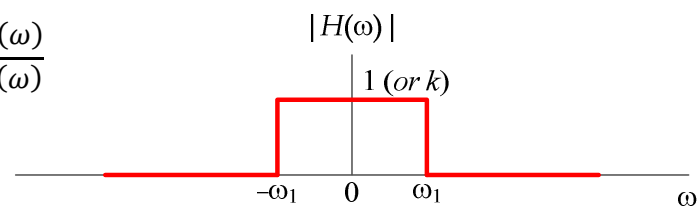


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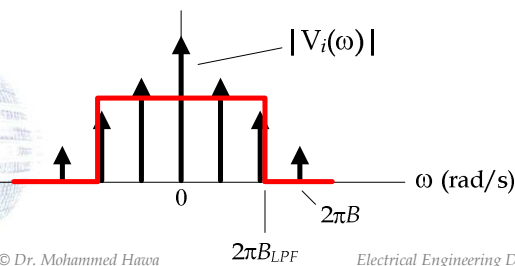
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Frequency-response function

$$H(\omega) = \frac{V_o(\omega)}{V_i(\omega)}$$



$$|V_o(\omega)| = |H(\omega)| \times |V_i(\omega)|$$

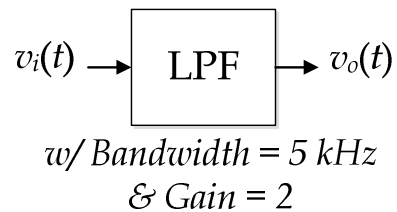


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Characteristics/Specifications

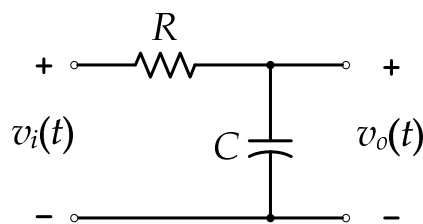
- Always centered at 0 rad/s.
- Bandwidth = Cut-off frequency = ω_1 rad/s
- Gain = k.



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Example Circuit



$$B_{LPF} = \frac{1}{2\pi RC} \text{ Hz}$$

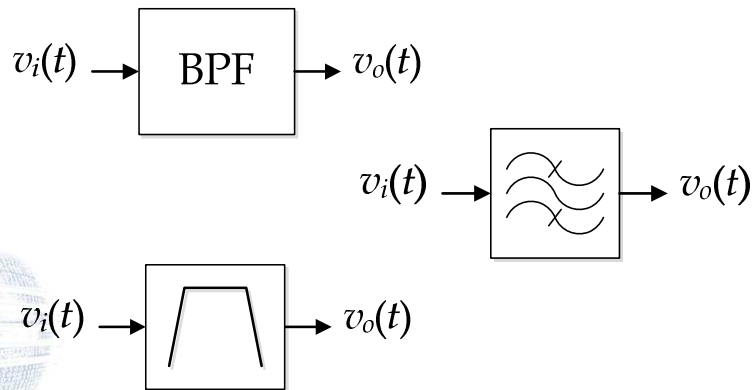
$$\text{Gain} = 1$$

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Band-Pass Filter (BPF)

- Symbol:

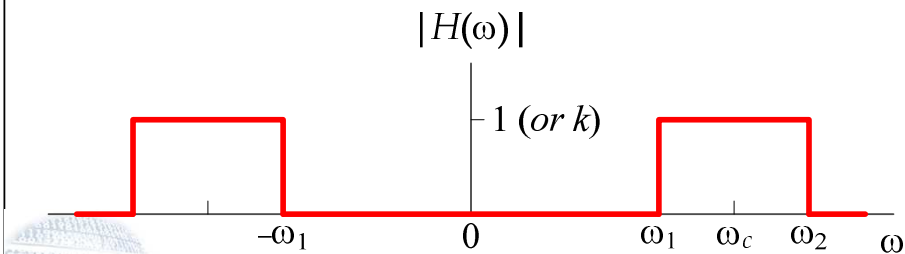


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Frequency-response function

$$H(\omega) = \frac{V_o(\omega)}{V_i(\omega)}$$



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Characteristics/Specifications

- Centered around center frequency ω_c rad/s.
- Bandwidth of Filter = $\omega_2 - \omega_1$ rad/s
- Gain = k.



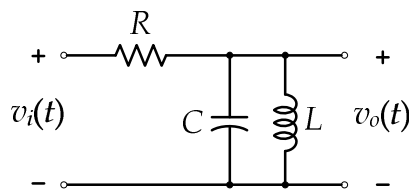
*w/ Bandwidth = 80 kHz
Center Frequency = 100 MHz
& Gain = 1*



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Example Circuit



$$f_c = f_{res} = \frac{1}{2\pi\sqrt{LC}} \text{ Hz}$$

$$B_{BPF} = \Delta f = \frac{R}{2\pi L} \text{ Hz}$$

$$\text{Gain} = 1$$



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