



# Time triggered handoff schemes in cognitive radio networks: A survey



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## ABSTRACT

Rapid development in wireless networks has largely raised the demand for spectrum bandwidth. However, current static spectrum allocation policy is unable to meet this ever-growing requirement which causes the spectrum scarcity problem. Cognitive radio network (CRN) has emerged as a grasping solution to scarcity problem where the secondary or unlicensed users are allowed to access the temporary free channels owned by the licensed or primary users. Among other important steps involved in a spectrum management process, handoff plays an essential role since it requires shifting the on-going transmission of a secondary user (SU) to a free channel without degrading the quality of service. An extensive work has been done in the field of spectrum handoff for CRNs. This work is mostly classified in timing, probability, and operating mode based handoff schemes. In this paper, we present a detailed classification and a compressive survey for time triggered handoff schemes. This topic is chosen because in time triggered handoff process, the handoff decision needs to be performed based on continuously sensing the arrival and departure patterns of licensed users, thus making it an important area of research. Therefore, we discuss the pros and cons for time triggered handoff schemes in detail.

## 1. Introduction

With rapid development of wireless networks, the demand for spectrum bandwidth has raised largely (Akyildiz et al., 2006). Number of devices utilizing the spectrum (licensed or unlicensed) is growing very fast in contrast to the availability of bandwidth. This spectrum scarcity problem occurred because the current spectrum allocation policy is static which is unable to accommodate the increasing bandwidth demands. In fact, the static allocation policy causes the licensed spectrum bands to be underutilized (FCC, 2003; Akyildiz et al., 2008).

Cognitive radio network (CRN) comes as an efficient solution to spectrum underutilization (Wang et al., 2011). A CRN enables a secondary, an unlicensed or a cognitive radio (CR) user, to utilize the temporarily unoccupied licensed bandwidth of a primary or licensed user in order to enhance the utilization of limited spectrum resources. CR maximizes channel utilization without effecting the well-established spectrum allocation regulation (Christian et al., 2012).

The main goal of cognitive radio (CR) technology is to allow unlicensed users to opportunistically utilize the spectrum holes (or white spaces) without disrupting communication of primary users (PUs). This opportunistic spectrum usage requires us to develop protocols and algorithms which can adapt to this highly changing environment. Moreover, due to the randomness in PU's behavior with

unpredicted arrival and departure timings, it is very difficult to achieve smooth spectrum usage to secondary users (SUs) and limited interference to PUs (Song and Xie, 2012).

Spectrum management process in CRNs usually consists of three different steps: firstly, since CR gets temporary access to available spectrum; therefore, it monitors the available channel and detects the spectrum holes by continuously examining the PU activities known as *spectrum sensing* (Sun et al., 2013; Akyildiz et al., 2011; Althunibat et al., 2015). Next up, there can be multiple SUs accessing specific channels; this access should be coordinated to avoid collisions among users known as *spectrum sharing* (Ahmad et al., 2015; Akyildiz et al., 2006; Mir et al., 2011). The third step is *spectrum mobility/handoff* (Wang et al., 2010; Christian et al., 2012) where an SU should continue its access on a vacant channel in case of arrival of the corresponding PU. Spectrum handoff is an important step in spectrum management process as it requires shifting the on-going transmission of an SU to another free channel without degrading the QoS (quality of service) of licensed users (Tayel et al., 2016).

As defined in Kumar et al. (2016), the triggering event is considered to be the main cause of handoff initiation. This triggering can be timing, CR user's mobility, probability, or operating mode based. In CR user's mobility based strategy, spectrum handoff can occur due to SUs mobility. This CR movement can be within the same cellular region without changing the current BS (base station) or to another cell,

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connecting to a new BS (Sun et al., 2016; Lee et al., 2012). In probability based handoff, the channel prediction probability is chosen to be the main factor for handoff decision (Tayel et al., 2015; Sheikholeslami et al., 2015; Yang et al., 2008). Thus, algorithms in these types of schemes are designed to predict the probability of future channel being idle or busy. With probabilistic estimates, sensing results are also used to make handoff decisions (Christian et al., 2012; Yang et al., 2008). Next is the operating mode based handoff process (Zhang et al., 2013; Feng et al., 2011). As mentioned in (Kumar et al., 2016), this handoff is divided in non-hopping and hopping categories. In the former, an SU does not perform a handoff in case of PU arrival and quietly stays on the current channel. In latter, the arrival of a PU may result in triggering of a handoff process and the affected SU may move to another channel. However, an SU may also decide not to perform handoff and stay idle on current channel. In timing based handoff schemes, both the effects of sensing decision and PU arrival rate are considered to trigger a handoff process. This type of handoff requires the movement patterns of PUs to be sensed and monitored carefully since the channel selection and handoff processes are to be performed based on the timing events triggered by a PU entering or leaving a channel. As per our knowledge and highlighted in (Kumar et al., 2016), time triggered handoff is very important in CR networks because it is based on the timing of spectrum sensing (Liang et al., 2008) and actual handoff process. Time triggered handoff can further be divided in four types (depending on sensing and handoff triggering time) such as non-handoff, proactive handoff, reactive handoff and hybrid handoff/adaptive handoff, respectively (Kumar et al., 2016). An extensive work has been done in recent literature in field of spectrum handoff in CRNs. To the best of our knowledge, at present, there is no detailed classification and comprehensive survey dealing with time triggered handoff schemes.

Moreover, we strongly believe that a handoff strategy should be developed by keeping in view the movements of PUs as an important design factor (Fahimi et al., 2016; Huang et al., 2015). Therefore, in this paper, we address the aforementioned in detail.

The main contributions of our paper are as follows:

- Spectrum handoff strategies based on time triggering are discussed individually in terms of features and limitations.
- Various figures and tables are drawn to present a comparative analysis.
- We present different performance criteria which are important in designing an efficient handoff strategy. We also highlight important papers addressing each of the mentioned criteria.

A list of all acronyms/abbreviations with their full form is provided in Table 1.

The rest of the paper is organized as follows. In the following section, we give a general overview of cognitive radio technology and the handoff process. Existing surveys addressing spectrum handoff process are summarized in Section 3. Time triggered handoff schemes are discussed in Section 4. In Section 5, important criteria for handoff strategies are detailed. Section 6 highlights the current and future research issues and challenges for time triggered and other handoff schemes in general. Our work is concluded in Section 7.

## 2. Overview of cognitive radio and handoff process

### 2.1. Cognitive radio: basic concept and importance

Currently, spectrum in wireless networks is governed by government agencies through a static assignment policy. Spectrum is assigned to licensed users usually for a longer period of time in large geographical areas. Spectrum is fully utilized in certain portions while a sufficient amount of licensed spectrum remains underutilized due to recently deployed static spectrum access policies (FCC, 2003; Akyildiz

**Table 1**

List of acronyms used throughout the paper.

Acronym/Abbreviation	Full form
AHP	Analytical Hierarchy Process
BS	Base Station
CCC	Common Control Channel
CDMA	Code Division Multiple Access
CRN	Cognitive Radio Network
CTMC	Continuous Time Markov Chain
CUWBIN	Cognitive Ultra-Wide Band Industrial Network
DFHC	Dynamic Frequency Hopping Communities
DSA	Dynamic Spectrum Access
FAHP	Fuzzy Analytical Hierarchy Process
FCC	Federal Communications Commission
FLB	Fuzzy Logic Based
FLC	Fuzzy Logic Controller
HMM	Hidden Markov Model
ISM	Industrial Scientific Medical
LTE	Long Term Evolution
MAC	Medium Access Control
MOTCSD	Modified Optimal Target Channel Sequence Design
NPRP	Non-Preemptive Resume Priority
PRP	Preemptive Resume Priority
PU	Primary User
QoS	Quality of Service
RF	Radio Frequency
SA	Spectrum Aggregation
SHCP	Spectrum Handoff based on Commutative Probability
SNR	Signal Noise Ratio
STBC	Short Time Backup Channel
SU	Secondary User
UWB	Ultra Wide Band
VoD	Video on Demand
WLAN	Wireless Local Area Network
WRAN	Wireless Regional Area Network

et al., 2008; Mitola, 2000). According to FCC (Federal Communication Commission) (FCC, 2003), at some point of a day, up to 85% of spectrum assigned to a licensed user may remain idle, showing a huge wastage.

As a result of above, modern-day wireless networks are moving from static and centralized control to distributed and autonomous networks (Khan et al., 2017; Clark et al., 2016), where the devices may work more dynamically and can opportunistically select the available spectrum by having frequent interactions and information exchanges with their neighboring devices. By autonomous networks, we mean that the control and information are fully distributed and wireless devices have the capabilities of self-organization and adaptability to cope with frequent network changes. Most commonly, the devices are meant to be infrastructure independent and are designed to enable inter-device interactions over single and multi-hop networks.

These autonomous as well as opportunistic behaviors are now becoming both possible and necessary by the introduction of cognitive radio technology in wireless networks. A cognitive radio (designed to follow a dynamic access policy) comes as an efficient solution to spectrum underutilization issue. Joseph Mitola defined cognitive radio in Mitola (2000) as “a radio that employs model based reasoning to achieve a specified level of competence in radio-related domains.” Generally, a CR (or a secondary user), considered to be an intelligent wireless network component that is aware of its surroundings through its sensing part, may adapt to the present environment by examining the radio frequency (RF) signals and can learn by interacting with its neighbors. Fig. 1 shows that a CR is basically aware of its radio environment, having the capabilities of adapting to these surroundings according to the changes it perceives. To adapt, a CR continuously senses or monitors its environment. It contains the knowledge of the priorities, procedures and needs of its users by learning over time and finally can generate the possible solutions in order to facilitate the necessary communications with its neighbors.

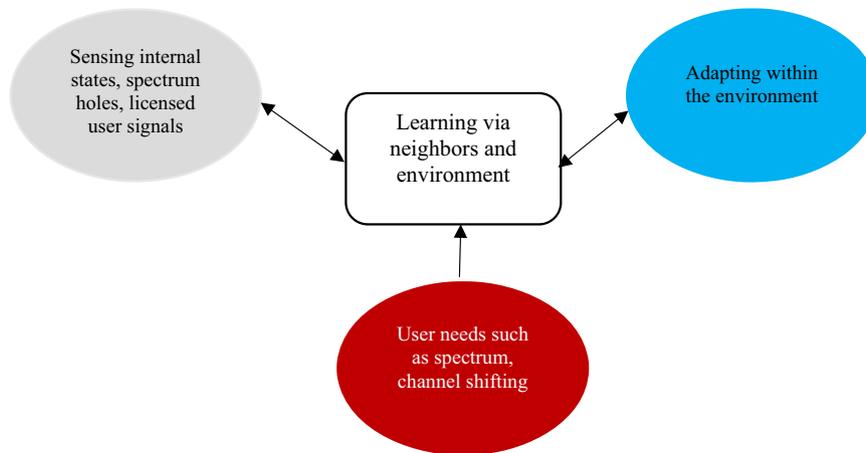


Fig. 1. Elementary functions of cognitive radio.

As detailed in Mitola and Maguire (1999), CR offers a novel way to solve static spectrum utilization problems. A CR senses the radio environment in order to identify those radio spectrum portions that are not in use by the legacy primary (or licensed) users and provides the incentives for making these unused bands available to perform the services required by the user. The unutilized spectrum portions are known as the *spectrum holes* or *white spaces*. In Haykin (2006), Haykin gave his assessment about a spectrum hole as “a band of frequencies assigned to a primary user, but at a particular time and specific geographic location, the band is not being utilized by that user.” It is obvious that the first priority to using these holes must always stay with the PUs and the CR user can only utilize it in an opportunistic and/or a negotiated manner without causing any interference to the relative PUs. Apart from licensed access, efficient spectrum sharing in unlicensed bands is also an important concern, which can be addressed via CR technology. The key attribute of unlicensed bands is their “openness” where the users can access the spectrum without license/right at any time. Moreover, due to a large amount of traffic in unlicensed bands, users have less incentives to access the free-to-use spectrum (Tonmukayakul and Weiss, 2005). Therefore, various collisions and conflicts can occur between the users, if unlicensed spectrum access is performed without coordination.

Normally, in CRNs channel utilization is maximized without affecting the well-established spectrum allocation regulations (Christian et al., 2012). The CR technology enables an SU to determine white spaces opportunistically through spectrum sensing feature. It also helps in detecting the arrival of PU in an SU’s operating channel. The best channel is then selected through the spectrum access (sharing) feature and finally, spectrum handoff decision enables an SU to shift its ongoing transmission to another vacant channel on the arrival of a PU. These CR functions are summarized in Table 2.

## 2.2. Handoff process in cognitive radio networks

Unlike traditional wireless networks, in CRNs a handoff should be

Table 2  
Brief description of each CR function.

CR Functions	Description
Sensing	Detection of unused bands or “spectrum holes” by sensing primary users signals
Access/Sharing	Accessing and sharing the available licensed (or unlicensed) spectrum between secondary users with or without coordination
Handoff	Leaving or vacating the licensed spectrum due to the arrival of corresponding licensed users

performed before the arrival and without interrupting the performance of PUs, thus requiring accurate sensing capabilities (Yucek et al., 2009). Inspired by our previously proposed work in (Mir et al., 2011), we draw Fig. 2 to depict the handoff process in CRNs. Two primary I and J and two secondary k1 and k2 users are taken for simplicity. In step 1 (as shown by double arrowed line), k1 and k2 are accessing the available band of J. In another instant of time, users k1 and k2 sense the arrival of primary user J (step 2). The two lines with circle heads depict the arrival of J. We assume, in this example, that users k1 and k2 have sensed another vacant band of primary user I (step 3), both the users now have to move to spectrum band 2 (step 4) to continue their transmission, thus the spectrum handoff process. This handoff process becomes more complicated with large number of users, thus requiring the development of sophisticated handoff management algorithms.

Spectrum handoff in CRNs is generally categorized in two major types as proactive and reactive. In the former, the channel selection is done based on detected traffic patterns of a PU, before the triggering event. In latter, the channel is selected by instant sensing after the occurrence of handoff triggering event. The secondary users affected by the handoff event can resume their transmission on a newly searched channel (Wang et al., 2009a; Wang et al., 2009b; Wang et al., 2009c). Thus, in both types of handoffs, the channel selection is done by continuously monitoring the signals of neighboring PUs. Some authors argue that it is sometimes desirable to have a combination of proactive and reactive handoff strategies to make one hybrid or adaptive solution (Hernández et al., 2015; Lee and Akyldiz, 2011; Wu et al., 2014). However, in most hybrid solutions, an SU always shifts the channel when a PU arrives. We believe that an SU may have the option of staying silently on a channel while PU is accessing it, this would reduce the number of unwanted handoffs. All these proactive, reactive, and hybrid strategies use time triggering as their essential feature, thus we detail the above mentioned and several other approaches in our forthcoming sections.

## 3. Related surveys

Recently, several surveys have been presented addressing the sensing and handoff related issues in CRNs. Table 3 presents a comparative summary of the existing surveys. The works presented in Akyldiz et al. (2008), Mwangoka et al. (2010), Verma et al. (2015) provide generalized surveys on spectrum mobility in CRNs. The purpose of these surveys is not specifically on time triggered handoff. The authors of Benmammam et al. (2013), Tragos et al. (2013) presented several dynamic spectrum access strategies in CRNs. These strategies are based on auction, game theory, multi agent systems, measurement models, network coded cognitive control channel, fuzzy logic, and Markov chains. Spectrum handoff is also discussed; however

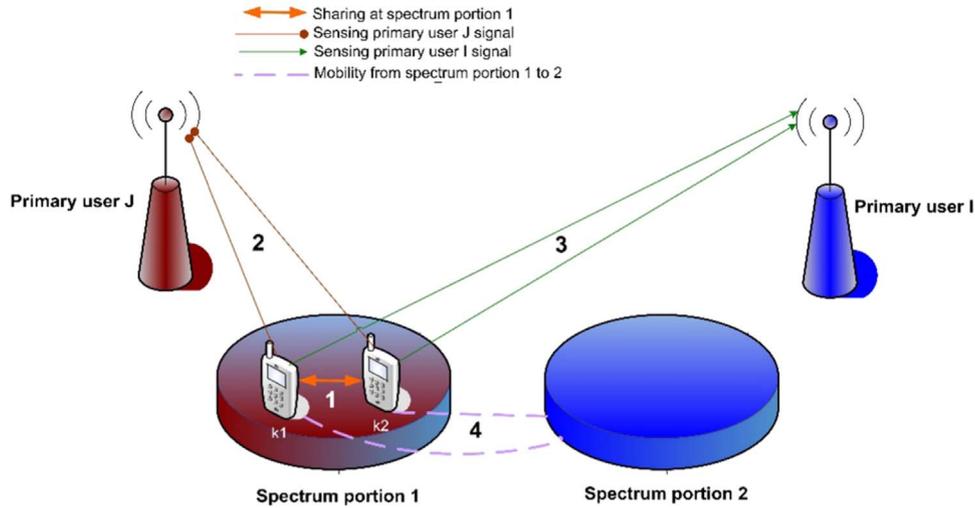


Fig. 2. Handoff process in cognitive radio networks (Mir et al., 2011).

the focus remains entirely on spectrum sharing. A few interesting proactive and reactive handoff solutions are also discussed in (Tiwari et al., 2016; Sajjan et al., 2015), however, the aforementioned do not detail time triggered handoff strategies as discussed in our work. A lot of interesting approaches are missing in Shokri et al. (2013), Sajjan et al. (2015) and the aspect of hybrid solutions is almost ignored. Another short survey is presented in Lertsinsruttavee et al. (2010) which classifies the spectrum handoff strategies for multiple channel CRNs. A classification of spectrum handoff in CRNs is presented in Kumar et al. (2016), where triggering is discussed briefly however, details are not comprehensive like our work. The authors divided the existing handoff strategies into different classes such as handoff triggered by timing, mobility, probability, and operating mode. They also identified some open research areas for each class including intelligent spectrum handoff, priority based spectrum handoff, spectrum handoff schemes based on green CRNs (Luo et al., 2015), interference avoidance, spectrum handoff reduction, and optimization of handoff information collection parameters. Several important proactive and reactive schemes were discussed in Kumar et al. (2016), however, a large amount of recent work remained untouched which we discuss throughout our next sections in detail.

#### 4. Time triggered handoff schemes

Time triggered handoffs are quite relevant to CRNs since the handoff decision totally relates to primary users activities. This requires handoff to be performed by continuously sensing the arrival and departure patterns of PUs thus, making the whole handoff process “time critical”. Other handoff schemes consider different factors to perform handoff decision such as CR user mobility, channel probability and operating frequency, however, in time triggered handoff, the actual timing of PU arrival should be considered to trigger a handoff event (Kumar et al., 2016). Therefore, the future of a CR user’s spectrum usage totally depends on how well it senses and monitors the activity of a neighboring PU (Saleem and Rehmani, 2014).

According to Kumar et al. (2016) and as shown in Fig. 3, time triggered handoff schemes can be classified in four types such as non-handoff, proactive handoff, reactive handoff, and hybrid handoff strategies, respectively. Recently, a lot of work has been done in the literature to address the time triggered handoff process which is detailed in our forthcoming subsections. However, before going into further discussion about existing time triggered handoff strategies, we depict the behavior of a CR user under time triggered handoff scenario in Fig. 4. The process starts with the detection of PU arrival and predicting PU stayed duration on its licensed channel via continuous sensing (Ali et al., 2016; Bajaj et al., 2016). One possibility for an SU is

Table 3  
Summary of various surveys addressing spectrum handoff/mobility.

Reference #	Topic	Handoff discussion	Classification	Handoff strategies	Timing based handoff strategies	Publication Year
(Akyildiz et al., 2008)	Spectrum Management	Yes	No	No	No	2008
(Mwangoka et al., 2010)	Mobility Management	Yes	No	No	No	2010
(Lertsinsruttavee et al., 2010)	Handoff Strategies	Yes	Yes	Yes	No	2010
(Benmamar et al., 2013)	Dynamic Spectrum Access	Yes	Yes	No	No	2013
(Tragos et al., 2013)	Spectrum Assignment	Yes	Yes	No	No	2013
(Shokri et al., 2013)	Handoff Strategies	Yes	Yes	Yes	No (categorization based on energy efficiency)	2013
(Ghosh et al., 2014)	Dynamic Spectrum Access	Yes	Yes	No	No	2014
(Verma et al., 2015)	Spectrum Mobility	Yes	No	No	No	2015
(Sajjan et al., 2015)	Mobility Management	Yes	No	Yes	No	2015
(Tiwari et al., 2016)	Proactive and Reactive Handoff	Yes	No	Yes	Only two	2016
(Kumar et al., 2016)	Handoff Strategies	Yes	Yes	Yes	Introduction (Only a few references related to time triggering)	2016

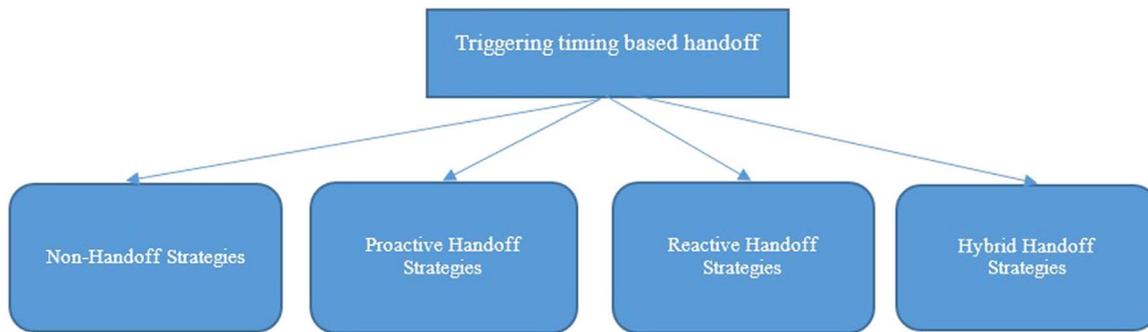


Fig. 3. A classification of time triggered handoff strategies.

to predetermine target channels for spectrum handoff, thus keeping a list of channels before transmission. This process is known as *Proactive Handoff*. A CR user can also decide to wait silently on current channel and allow the PU to finish its transmission and leave the channel. This type of time triggered handoff is called as *Non-Handoff*. A non-handoff strategy should be designed in a way that a CR user's signal should not affect the transmission of the PU since both types of users co-exist on the same channel simultaneously. In another form of time triggered handoff, an SU can leave the channel at the time when the PU arrives.

This type of handoff is known as *Reactive Handoff*. Sometimes it is better to use the combination of both proactive and reactive handoff strategies, thus making a(n) *Adaptive/Hybrid* strategy. We discuss all important algorithms/strategies related to non-handoff, proactive, reactive and hybrid/adaptive handoff types in the subsequent sections.

4.1. Non-handoff schemes

In a non-handoff technique shown in Fig. 5, on the arrival of a PU,

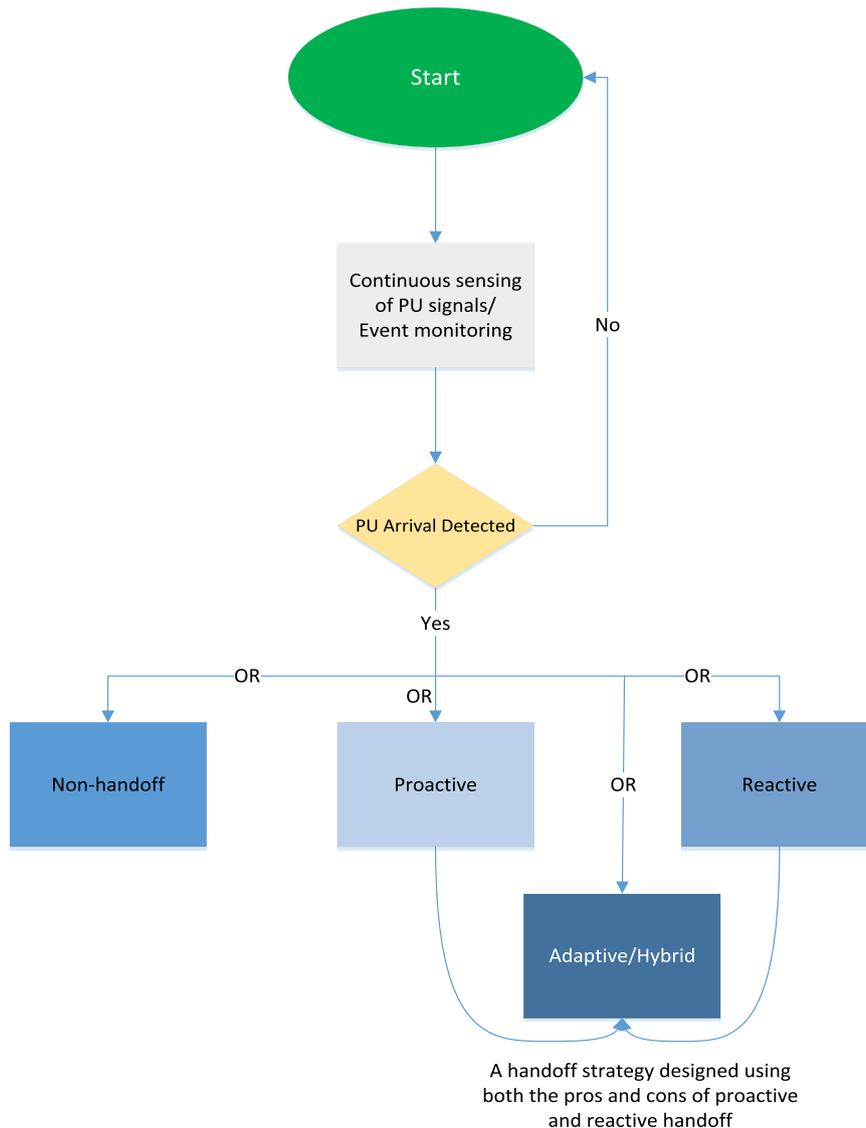


Fig. 4. Adaptation of a CR user to different time triggered handoff types based on PU activity.

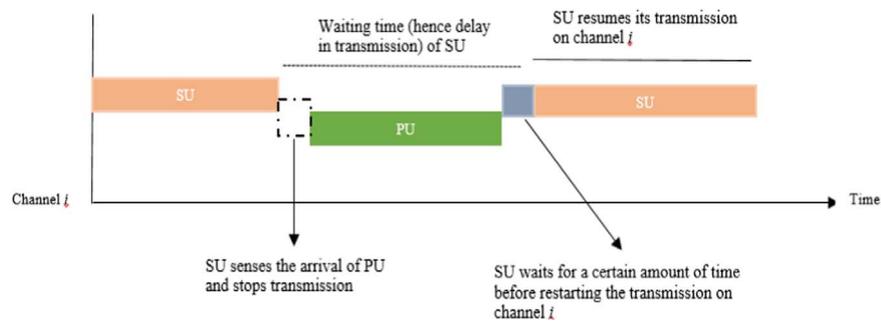


Fig. 5. Non-handoff process considering one SU and one PU.

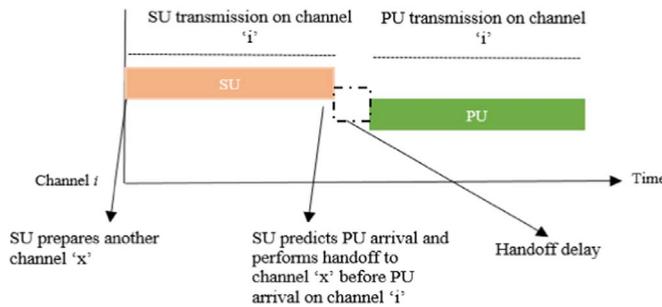


Fig. 6. Proactive handoff process at channel 'i' inspired by Christian et al. (2012).

an SU stops its transmission and waits on the current channel "i" for PU to complete its transmission. When PU leaves, the corresponding SU can resume its transmission on channel i. The process continues until SU completes transmitting on channel i. This handoff technique is similar to the non-hopping approach of IEEE 802.22 (Hu et al., 2007b). The main feature for a non-handoff algorithm is to have a very low interference with a PU because the data transmission of an SU is fully dependent on PU's activity. Moreover, the cost for searching another vacant channel and performing handoff is eliminated because an SU does not shift the channel, however, a non-handoff strategy may suffer from unpredictable waiting latency since a PU can stay on a channel for a pretty long duration.

The authors of (Wang et al., 2009a; Wang et al., 2009b; Wang et al., 2009c; Wang et al., 2011; Zahed et al., 2013) adapted a non-handoff behavior in their proposed models. Normally, in a non-handoff process, the average handoff delay for an SU's transmission is the average period a PU occupies a channel. In Zahed et al. (2013), it is argued that performing handoff is a time consuming process since SUs have to search for other channels and reconfigure their operating parameters accordingly. Thus, authors believe on the idea of avoiding handoffs at PU arrival and staying and waiting silently on a channel unless the corresponding PU finishes its transmission. In the proposed model of Zahed et al. (2013), SUs having interruption in their transmissions (due to PU arrival) should maintain priority queues where they have to wait unless PU leaves the channel and other uninterrupted SUs finish their transmissions. This waiting time adds an extra delay, however, it reduces users collisions in accessing a channel.

In Wang et al. (2009a, 2009b, 2009c), the authors compared cumulative handoff delay for non-handoff and random selection handoff strategies. These two approaches are renamed as "always staying" and "always changing" strategies, respectively. In an always staying approach, the target channels are predetermined since an SU does not perform a handoff. For an always changing scheme on the other hand, future channel has to be determined randomly on PU arrival (thus, this approach can also be classified under proactive handoff category). Through experiments, it is shown that with higher value of PU arrival, the random selection has more cumulative handoff delay compared to the non-handoff scheme. This delay is usually because the interrupted SUs with random selection method must wait for longer periods when

changing their operating channels since the "selected target channels" are likely to be busy. Another important non-handoff strategy is given in Christian et al. (2012) which is detailed in the survey presented in Kumar et al. (2016).

Like above, in Wang et al. (2011) load balancing is considered to be the primary goal for channel selection. At first, the optimal number of channels is sensed using CR sensing capability. Later, the best/optimal channel selection is done using probability based analysis. The prime objective of authors is to minimize the overall system time which remains at lower side due to the non-handoff policy adapted in Wang et al. (2011).

#### 4.2. Proactive handoff schemes

In proactive handoff strategies (Fig. 6), the future channel for data communication is determined according to the detected traffic patterns of a PU, before the handoff triggering event. Prior to the arrival of a PU, an SU can shift its on-going transmission to another backup channel reducing the transmission delay. There is a lot of work done for proactive handoff in the current literature. For the sake of simplicity and explanation, below we divide the existing literature on proactive handoff in several subsections. In addition, the pros and cons of the proactive approaches are summarized in Table 4.

##### 4.2.1. Short time backup channel (STBC)

Short time backup channel (STBC) is a proactive handoff strategy proposed in Lertsinsruttavee et al. (2010) where the backup channel for SU transmission is selected before the PU arrival. The handoff decision in STBC is dependent on the QoS of current channel. If the current channel meets the transmission (or QoS) requirements of an SU, the backup channel is released. Otherwise, the SU has to shift its transmission to the backup channel. Proposed strategy keeps the backup channel for a short duration so it achieves better bandwidth utilization compared to schemes maintaining a permanent backup channel. A minimum level of handoff delay can be achieved by STBC as compared to approaches with no backup channel because the target channel is selected before the occurrence of handoff triggering event. However, maintenance of backup channels results in bandwidth underutilization as well as a high algorithmic complexity since users have to manage current and backup channels simultaneously. Some other proactive schemes based on the idea of "not-using" a common control channel (CCC) for SUs communications are proposed in Song and Xie (2011, 2012), respectively. The information about these schemes are already given in Kumar et al. (2016) quite comprehensively, therefore we skip the details here. In addition, the authors of Bicen et al. (2015) analyze the performance of CR handoff management system with and without the inclusion of a common control channel. Through extensive analytical and experimental results, it is revealed that the addition of a CCC leads to an additional delay, however, under ad-hoc network conditions, adding CR nodes is more costly than incorporating a CCC.

**Table 4**  
Summarized list of pros and cons of several proactive handoff schemes.

Pros and Cons of Proactive Handoff Schemes		
Approach/ (acronym)	Advantage	Limitation
<b>STBC</b>	Minimization in handoff delay compared to approaches with no backup channel	Design and algorithmic complexity
<b>Fuzzy logic based schemes</b>	<ul style="list-style-type: none"> <li>● Maximum channel utilization</li> <li>● Thorough comparison with existing random handoff schemes proves that SUs get their maximum throughput</li> </ul>	<ul style="list-style-type: none"> <li>● No learning via environment</li> <li>● Wastage of backup channels</li> <li>● No robustness</li> <li>● Design and architectural complexity</li> <li>● Hardware overhead</li> </ul>
<b>CPSH Markov based approaches</b>	QoS is high <ul style="list-style-type: none"> <li>● Accurate sensing using Markov models</li> <li>● Well defined states of channel usage, idle transmission and handoff for a user</li> <li>● SUs can access a channel in the presence of PUs</li> </ul>	Wastage of backup channels <ul style="list-style-type: none"> <li>● Limited comparison with existing solutions</li> <li>● In some solutions, despite collision avoidance, SUs signal can still affect the transmission of PUs which is unacceptable</li> <li>● Only one or two authors model the handoff process in continuous time</li> </ul>
<b>MOTCSD</b>	Overall processing (sensing and handoff) time is at minimal level	Traditional limitation of SUs acting greedy at times

#### 4.2.2. Fuzzy logic based (FLB) proactive handoff

An interesting Fuzzy logic based proactive spectrum handoff scheme is presented in [Giupponi et al. \(2008\)](#). The main purpose of fuzzy logic is to handle problems more efficiently compared to mathematical models. The proposed algorithm is based on two Fuzzy logic controllers (FLCs). The first controller is there to measure the distance between PUs and SUs. It also estimates the transmission power for an SU so that it should not affect the transmission of neighboring PUs. The second controller is designed to check whether an SU should stay on the current channel or leave. A handoff is initiated, if the QoS for an SU is not up to the mark and thus, the SU is causing considerable amount of interference to the transmission of neighboring PUs. The main advantage of this strategy is the use of Fuzzy logic which provides an efficient estimation of handoff decision parameters such as QoS and transmission power of an SU and its interfering effects on a PU's transmission. Moreover, since no backup channel is used in this approach, the channel utilization remains maximal, however, the use of FLCs makes this approach suffer traditional limitations of having no robustness and overall architectural and design complexities.

A proactive handoff scheme is presented in [Yi et al. \(2014\)](#) that applies Fuzzy analytic hierarchy process (FAHP) for the handoff decision. This strategy reserves a number of backup channels in advance with the current operating channel. The pre-determined channels are characterized on the basis of required QoS and continuing validity indicators. The authors present extensive simulations to analyze proposed FAHP on the basis of switching frequency, overall system throughput and system delay. Comparisons with traditional random handoff schemes reflect that FAHP effectively reduces the latency and number of handoffs while improving the overall system throughput, but no limitations are identified in the results. We believe that this approach also suffers with the same drawbacks mentioned above for FLC based proactive approach ([Giupponi et al., 2008](#)).

#### 4.2.3. Commutative probability based spectrum handoff (CPSH)

The authors of [Lertsinsruttavee et al. \(2011\)](#) proposed a proactive handoff strategy that is based on cumulative probability (CPSH). In this technique, a PU decides on whether to stay on its current operating channel or perform handoff depending on the results of probability estimation algorithm. According to this algorithm, an SU performs a handoff when: 1) a PU comes back to its licensed channel currently occupied by an SU; 2) the current channel does not meet the bandwidth requirements for an SU to continue its transmission; and 3) the quality of new channel is better than the current one (in terms of throughput). Another improvement in the proposed model is the use of a backup channel for a short duration (very much similar to [Lertsinsruttavee et al. \(2010\)](#)). If the current channel meets the transmission requirements for an SU, the backup channel is released to maximize the

channel utilization, thus, providing a better QoS and minimum handoff delay for SUs. Though, backup channel is used for short durations, it can still result in channel underutilization since it remains free unless and until an SU initiates transmission on it.

#### 4.2.4. Markov Models for proactive spectrum handoff Handoff

Random appearance of a PU can sufficiently degrade the ongoing communication of an SU on a specific spectrum band. This disruption in transmission can lead to lower throughput in CRNs. To cope with this challenge, the authors of [Pham et al. \(2014\)](#) propose a hidden Markov model (HMM) based scheme to optimize handoff decision in CRNs. HMM is used to correct the spectrum sensing sequence in order to enhance the spectrum opportunities for SUs and check the state of a channel. Experimental results show the performance gain achieved by SUs with less probabilities of misdetections and false alarm.

UWB (ultra wide band) technology has gained attention recently due to its significance in short range communications. Keeping in view the pros of UWB technology, the authors of [Tran et al. \(2015\)](#) present a handoff strategy for cognitive ultra-wide band industrial networks (CUWBINs), where an SU can coexist with a PU on a channel. The busy and idle periods of a channel are modeled by developing Markov chains. This strategy avoids the collisions between SUs and its dynamic and diverse nature provides seamless connectivity to users. Through simulations, it is shown that the proposed proactive handoff models achieve less handoff delay as well as increased handoff efficiency compared to existing schemes which do not utilize UWB in their design process. However, as stated in [Clancy et al. \(2007\)](#), the coexistence of SUs with PUs results in lower throughput for users.

In [Min et al. \(2011\)](#), the authors propose a 2-state CTMC (continuous time Markov chain) to model the channel availability for SUs by taking in account the secondary user's mobility. A concept known as "guard distance" is introduced which is basically an additional separation between primary and secondary users. The purpose of guard distance is to prevent interference on PU transmissions. This guard distance is then optimized with the "sensing time" to maximize the opportunities in spectrum reuse. Likewise in [Zhu et al. \(2007\)](#), Markov models are presented with focus on calculating the forced termination and blocking probabilities in scenarios when an SU may or may not perform a handoff. Another related survey having details of Markov and similar prediction schemes can be found in [Xing et al. \(2013\)](#).

An approach allowing SUs to opportunistically operate on various vacant PU channels is presented in [Wu et al. \(2016b\)](#). The algorithm allows an SU to predict the channel status and decide to stay idle on the current channel or perform handoff, respectively. The whole channel access and handoff scenario is modeled using a discrete time Markov chain that minimizes the total cost of an SU for a specific transmission. Moreover, the proposed strategy achieves a better data transmission

efficiency and energy consumption as compared to always staying and always changing handoff schemes (Wang et al., 2009a, 2009b, 2009c).

#### 4.2.5. Modified optimal target channel sequence design (MOTCSD)

Wang et al., presented an interesting greedy algorithm in Wang et al. (2012) which is based on proactive selection of target channels. Based on network status, the algorithm allows SUs to select suboptimal channels by comparing six different mathematically generated sequences (for details please refer to Theorem 2 and Fig. 5 of Wang et al. (2012)). The authors of Zakariya et al. (2015), on the other hand, believe that instead of six sequences discussed in Wang et al. 2012, a set of five target channel sequences are enough for the production of suboptimal greedy behavior (one of the six sequences is “redundant”). This modification can minimize the processing time spent during optimal target channel selection especially where the candidate channels are huge in numbers as reflected in presented results. Moreover, the algorithm of Zakariya et al. (2015) can sufficiently decrease the probability of selecting the worst channel which was not addressed in Wang et al. (2012).

#### 4.2.6. Other proactive approaches

Beside above, there are some other important strategies which are based on proactively sensing the channels and taking handoff decisions. In Shokri and Fischione (2015), an efficient spectrum access policy is developed which allows SUs to create a random order for the available channels (before PUs arrival/return), and then find optimal transmission and handoff opportunities in a distributed manner. In Kahraman et al. (2015), Song et al. (2010), the authors model the spectrum handoff process as a continuous time Markov chain with a focus on achieving minimal handoff delay. In Mehrnough et al. (2017), SUs are allowed to cooperate at several rendezvous points to share the information about PUs activity. All this activity is done proactively before the arrival of PUs. Multiple rendezvous points allow flexibility in SUs cooperation and thus the proposed approach achieves higher throughput than single rendezvous schemes discussed in Mehrnough et al. (2017). Another interesting proactive handoff scheme is proposed in Dulaimi et al., (2016). The authors introduce a novel concept of a channel assigning agent (CAA) under LTE (long term evolution)/WLAN cognitive radio network. The CAA is responsible for allocating channels to CR users as well as handling their movements from one cell to another. Unlike other proactive approaches, the inclusion of CAA in Dulaimi et al. (2016) simplifies the handoff management process since the duties of user registration, channel information storage, and seamless handoff management are performed by CAA. This performance gain is shown through experimental results in the form of reduced number of handoffs.

#### 4.3. Reactive handoff schemes

In reactive handoff strategies, the future channel is selected by instant sensing after the occurrence of handoff triggering event. An SU can continue its paused transmission on newly searched channel (Haykin, 2007). The whole reactive process can be seen in Fig. 7 where an SU senses and then moves to channel 2 at PU arrival. The advantage of reactive handoff is the accuracy in selecting the target channel, but as the selection is made from the results of on-demand wideband sensing therefore, reactive approaches mostly suffer with an additional cost of sensing time (Wang et al., 2011). Moreover, the handoff delay also increases because the sensing is started after the handoff triggering event. We detail existing reactive solutions as follows.

##### 4.3.1. Coordination and M/G/1 queuing models for reactive handoff

The authors of Hu et al. (2007a) proposed a reactive handoff scheme named as dynamic frequency hopping communities (DFHC). This strategy is supposed to increase IEEE-802.22 performance in terms of QoS requirements of SU while providing reliable and timely

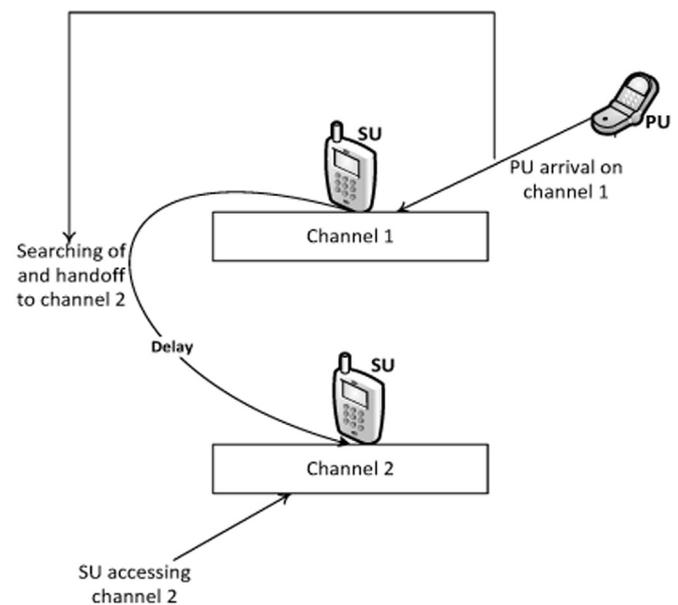


Fig. 7. Reactive handoff process from channel 1 to channel 2. Different type of devices are used to differentiate between an SU and a PU.

spectrum sensing for guaranteeing the PU protection. A WRAN (wireless regional area network) cell (or an SU) while communicating on current channel observes availability of the next target channel. A coordination mechanism is also proposed in this scheme to avoid interference among SUs during sensing phase. Generally, a community leader manages the set of  $n$  coordinated SUs in DFHC. The SUs interchange sensing information by the coexistence window which is available at the end of a MAC (medium access control) frame. Another coordination based scheme is presented in Vijayakumar et al. (2014) for Zigbee CRNs in which an SU can access multiple channels via periodic sensing and spectrum handoff. The authors divide their work in two sections; the monitoring section to obtain the received signal strength and the controlling section to evaluate the obtained result to declare SU presence or absence. For sensing process, an energy detection algorithm (Chatterjee et al., 2015) is used that compares the received signal's energy with a properly set threshold. If energy is more than the threshold, then the arrival of PU is declared. The handoff is performed by comparing the energy level of a channel with defined threshold.

Like coordination, developing queuing models is also considered to be an efficient way for handoff management. Thus, in Wang et al. (2012, 2010)<sup>1</sup>(Talat et al., 2016) M/G/1 queuing models are proposed to improve the channel usage of SUs. Each SU can simultaneously use multiple available channels for its transmission. Since, the availability of channels directly depends on traffic patterns of a PU, therefore service time is distributed non-trivially. M/G/1 queues are used to model the aggregated arrivals of all SUs sharing the available channels. Further, the proposed model in Wang et al. (2012) considers two situations; 1) when the number of SUs accessing the channels is greater than the available channels, then some users must wait for the channel to become free and 2) when the number of SUs is less than the available channels, the packets waiting time remains minimal. The authors of Talat et al. (2016), on the other hand, focus on minimizing the overall system time for SUs. This time is defined as a sum of transmission time and waiting time. Through simulations, the authors prove the reduction in overall system time as well as consistency between the results obtained via probabilistic M/G/1 model and experiments. Another priority M/G/1 queuing based reactive handoff scheme is proposed in

<sup>1</sup> Details about this work are thoroughly discussed in Kumar et al. (2016).

Wang et al. (2009a, 2009b, 2009c). In the considered scenario, the PUs and SUs transmit on the same channel simultaneously until and unless an SU causes interference to a PU, resulting in handoff for the corresponding SU. The channel usage patterns and behaviors of primary and secondary users with multiple spectrum handoffs are categorized using M/G/1 queuing. The authors of Shankar (2007) focus on the aspect of cross layer optimization in order to search for an alternate channel at PU arrival. M/G/1 modeling is used to analyze the transmission performance of SUs for Physical and MAC layers on an aggregate basis.

Both coordination and M/G/1 strategies maximize channel usage and user throughput by deploying efficient coordination and queuing mechanisms, however, handoff delay and waiting time for SUs are increased as the handoff decision is taken after the PU arrival. Moreover, the solution of Vijayakumar et al. (2014) provides better results when the noise is at minimal level, but as the energy detector cannot distinguish between a PU's signal and noise, therefore, a false alarm can be triggered causing unnecessary handoffs. Under multipath fading or shadowing, a CR user requires higher detection capabilities to tackle with the channel randomness which can be provided by cooperation mechanisms (Cabric et al., 2004; Gandetto et al., 2007).

#### 4.3.2. Other important reactive handoff schemes

In Willkomm et al. (2005), an interesting reactive scheme is proposed with the focus on throughput maximization of SUs. An SU holds multiple available channels simultaneously and instead of utilizing a whole channel, an SU performs its transmission on multiple sub-channels. When a primary user wants to reclaim all the capacity of its channel, the SU then has to search for another vacant channel to continue its transmission. Through experiments the authors show that their reactive algorithm results in efficient throughput achievement for SUs with a low frequency of handoffs, however, this approach suffers with the complexity of dividing a channel in multiple sub-channels and then avoiding interference to corresponding PUs on each of the sub-channels. Different from Willkomm et al. (2005), a slightly recent work proposed in Tian et al. (2014) allows SUs to select future channels (on PU arrival) based on two criteria; the predicted probability of whether the target channel is idle or busy and the length of period for which a channel remains occupied by a PU. If a channel is idle and has shorter busy period, then a handoff is performed on that channel. This decision is then communicated to neighboring SUs. The proposed reactive scheme sufficiently reduces the number of handoffs, however, it requires efficient sensing to monitor the time a PU actually stays on a channel since the handoff decision is totally based on the length of a busy period. Moreover, the communication exchange between SUs also causes an extra overhead.

The authors in Oliaee et al. (2014) propose an interesting reactive handoff approach by introducing realistic channel switching capabilities, where the SUs can only switch to neighboring channels without inducing high latencies. Here, by realistic it means that SUs can only switch to those neighboring channels which are within their frequency range. This is unlikely to happen in other reactive approaches where any channel can be selected at PU arrival without considering device's operating frequency. CTMC models are used to derive the forced termination and blocking probabilities for CR users. Through results, it is shown that increasing PU arrival rate has a direct impact on blocking and forced termination probabilities which is (kind of) an obvious trend.

Normally, most of the above reactive solutions are developed for situations where an SU's transmission is interrupted by a PU only once, thus ignoring the case of multiple PU interruptions. This important concern is addressed in Premarathne et al. (2017) where a delay sensitive reactive strategy is presented for the SUs having multiple interruptions by neighboring PUs. An SU is allowed to access a channel more than once in different time slots. Moreover, an SU should

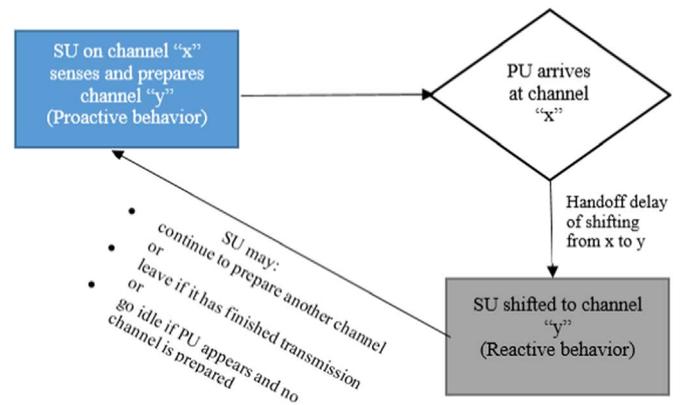


Fig. 8. A simple example showing an SU performing hybrid handoff decisions. For simplicity two channels x and y are considered.

complete its multiple transmissions within a specified time delay which is unlikely to happen in most of the above presented reactive approaches. Through mathematical analysis, the authors calculate buffer size, capacity of a fading channel, average delay in transmission, spectrum access of an SU, and waiting time. Experimental results show that the proposed approach incurs less delay especially for SUs having multiple interruptions.

#### 4.4. Hybrid/adaptive handoff schemes

The schemes we discussed so far are either proactive or reactive in nature. One important aspect recent researchers have focused on, is to combine the benefits of both proactive and reactive handoff schemes to develop an efficient hybrid/adaptive solution. Both words “hybrid” and “adaptive” can be used interchangeably, however, as discussed in our recent work (Mir and Munir, 2017), we differentiate between the two terms for the sake of explanation and classification. In a hybrid approach (shown in Fig. 8), sensing of a primary user's signals and handoff decision are both performed jointly in proactive and reactive manners, respectively. By continuous sensing, the target channel is selected proactively and the handoff is performed at the occurrence of triggering event, thus shifting to a (proactively) selected channel reactively on the arrival of a PU. In an adaptive solution (shown in Fig. 9), “the decisions of channel selection and handoff are made by continuously monitoring the arrival and departure patterns of a PU. When a PU is moving quite regularly, an SU may adapt to reactive handoff strategy. While in case of rare PU movements, a proactive handoff solution is preferred by the corresponding SU. Thus, a secondary user can either choose between proactive or reactive approach based on the frequency of PU arrival and departure (Mir and Munir, 2017).” Below we detail various hybrid and adaptive handoff schemes.

##### 4.4.1. Hybrid solutions

Spectrum aggregation (SA) allows a PU or an SU to simultaneously utilize multiple spectrum bands in order to satisfy increased bandwidth demand and achieve better performance in terms of QoS (Wang et al., 2010). CR being an intelligent radio can sense and utilize the available white spaces by examining the radio environment (Akhtar et al., 2016). This sensing quality makes it possible to combine the idle channels by spectrum aggregation. A hybrid handoff scheme is proposed in Yin et al. (2013), which is based on dynamic spectrum aggregation to identify the behavior of an SU during a handoff process. Whenever PU comes back to its licensed channel, the SU performs handoff to any other backup channel. All the channels other than the current channel are backup channels for an SU which can be either idle or utilized by a PU. An SU will wait for the completion of PU transmission if a channel is found busy. An SU should choose minimum handoff probability to

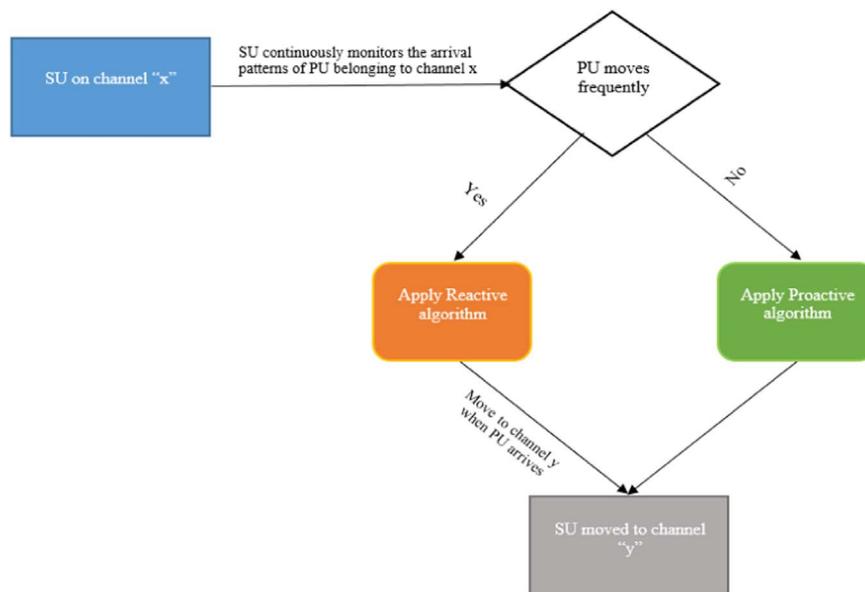


Fig. 9. An adaptive handoff strategy.

reduce the number of handoffs. To minimize handoff delays, backup channels can be used, however, as previously mentioned, this might result in “channel underutilization.”

As presented in Yin et al. (2013), the hybrid scheme proposed in Dahiya (2014) allows SUs to take a proactive or a reactive handoff decision on the basis of PU arrival rate as well as network parameters such as QoS and bandwidth. The combination of these parameter values along with PU arrival rate on current channel are compared with those of the neighboring sensed channel(s). Handoff decision is performed if the future channel provides higher QoS and bandwidth to an SU. Simulation results show that the proposed hybrid handoff scheme reduces the blocking probability and handoff delay for real-time services; however, it increases the waiting time and blocking probability for non-real time services since SUs have to wait quite a lot to get access to a channel.

The authors of Wu et al. (2014) presented a hybrid handoff scheme to maximize the QoS experience of multimedia centric SUs. An SU adaptively senses and selects the target channel before PU arrival and performs the handoff action after the triggering event depending on the varying channel conditions and QoS requirements. A mixed preemptive and non-preemptive resume priority (PRP and NPRP) queuing model is developed to provide differentiated multimedia services to SUs. The PRP captures the interactions between PUs and SUs, while the NPRP queuing is used to depict the behavior of an SU. The proposed queuing model allows the (so called) high priority SUs to continue their transmission without being interrupted by the neighboring SUs, thus achieving high QoS for users running multimedia based applications. Nevertheless, sometimes SUs with no multimedia services have to stay in a waiting queue for long durations, which increases the overall waiting time. Different from Wu et al. (2014), the algorithm presented in Hernández et al. (2015) combines the analytical hierarchy process (AHP) (Hernandez et al., 2015b) and technique for order of preference by similarity to ideal solution (TOPSIS) (Hernandez et al., 2015a) to perform a handoff decision. AHP evaluates the decision criteria for the selection of best target channel while TOPSIS evaluates all available channels and arrange them from best to worst. Best channel for handoff is selected on the basis of channel availability probability, estimated duration of availability, available bandwidth, and SNR (signal to noise) ratio. Despite being an interesting hybrid algorithm, the proposed simulations are vague and presented results have not been justified properly. Another hybrid scheme is presented in Lala et al. (2013) exploiting the benefits of both proactive and reactive

decisions, however, this approach suffers with the traditional drawback of large number of handoffs at PU arrival.

#### 4.4.2. Adaptive solutions

Unlike reactive, proactive, and hybrid solutions, adaptive handoff approaches are rare to find in the existing literature. In this context, an adaptive handoff strategy is presented in Lertsinsrubtavee et al. (2014) which combines both static and dynamic spectrum access features. In static access, the handoff action is not performed during the transmission of an SU. The channel is assigned only once at the start of transmission. Whereas in dynamic access, an SU can change the operating channel on the arrival of a PU to complete its transmission, thus trying to achieve the objective of maximal channel utilization (Lee and Akyldiz, 2011). Based on the network configuration and PU activity modeling (via heuristics), an SU can shift between static and dynamic modes, respectively. Thus, adapting to a static mode when the channels are idle and shifting to a dynamic mode when PU arrivals are frequent. Slightly different from Lertsinsrubtavee et al. (2014), in Pham and Chong (2013) the available channels are detected proactively via periodic sensing. After channel selection, the periodic sensing is stopped and whole available time is dedicated to the SUs transmissions. On PU arrival, the transmission of an SU is shifted to the next selected channel. If next channel is busy, then on-demand sensing (as in reactive handoff) is performed to look for another vacant channel, thus, adaptively adjusting to various sensing and handoff modes according to PU activities.

The above two strategies suffer with the traditional limitations of large waiting time, poor channel utilization, and unproductive handoffs. We tried to address these limitations in our recent work published in Mir and Munir (2017). We apply energy detection sensing (Chatterjee et al., 2015) to sense PU arrivals (this type of sensing is less complex in implementation (Cacciapuoti et al., 2015)). In case of performing a handoff, the data delivery time (Pandya et al., 2015) for proactive and reactive handoff decisions is calculated and the scheme with minimum data delivery time is applied for proper handoff function. This important factor was ignored in Lertsinsrubtavee et al. (2014) and Pham and Chong (2013). Another promising feature of our strategy is to model the overall handoff process using CTMCs (Wang et al., 2009a, 2009b, 2009c) which can capture the system evolution dynamics, especially the effects of PU arrivals on SU services. It is shown through extensive simulations that the proposed continuous time models and adaptive nature of algorithm based on data delivery

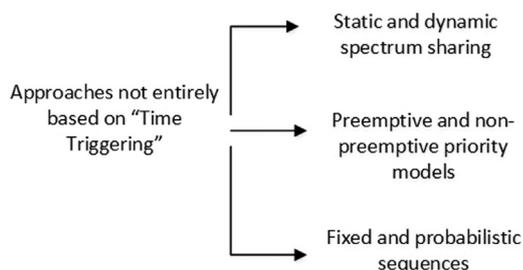


Fig. 10. Approaches based on other factors than "time triggering".

time allow SUs to achieve high spectrum usage, less unproductive handoffs, and minimum waiting delays compared to various existing solutions mentioned above.

Beside all the schemes discussed so far, there are some important ones which are worth mentioning here, however, we are not detailing these strategies because they do not fit into the category of "time triggered handoff." These important works are shown in Fig. 10 and are a combination of static and dynamic spectrum sharing, fixed and probabilistic sequences, and preemptive and non-preemptive resume priority, respectively.

## 5. Performance criteria for handoff strategies

In this section, we briefly discuss the important performance factors (or criteria) which can seriously affect the performance of a handoff strategy in CRNs. These criteria are chosen by thoroughly examining the existing literature. For the scope of this work, we mostly focus on "time triggering" strategies, however, these criteria are equally important and addressed in all other handoff management approaches.

### 5.1. Number of handoffs

Spectrum handoff occurs very frequently in CRNs depending on the patterns of primary users. These handoffs can sufficiently decrease the performance of an SU by adding an additional delay and latency in transmission. This may seriously degrade the battery life and energy of an SU device. According to Byun et al. (2008), on average 96% of device's energy is consumed in a single spectrum handoff process (Byun et al., 2008). Therefore, decreasing the number of handoffs is an important performance criterion to consider in design of handoff strategies. The schemes reported in (Kahraman et al., 2015; Wang et al., 2012; Yin et al., 2013; B. Wang et al., 2009; C.W. Wang et al., 2009; C.-W. Wang et al., 2009; Yi et al., 2014; Zahed et al., 2013; Mir and Munir, 2017; Hu et al., 2007a; Tian et al., 2014; Wu et al., 2014) thoroughly focus on minimizing the number of handoffs in CRNs.

### 5.2. Channel utilization

Bandwidth is a limited and important resource in wireless communications. As discussed several times, the purpose of a CR user is to efficiently utilize the available channels to mitigate the effects of overall spectrum scarcity. Thus, efficient channel utilization is an important design and implementation factor for CRNs and this importance becomes more critical in highly frequent handoff conditions. Spectrum handoff strategies have to be designed without ignoring the overall channel utilization. Almost all the works discussed so far consider channel utilization as a part of their design and implementation process.

### 5.3. Handoff delay

Handoff delay is the time an SU takes to pause an ongoing transmission on arrival of a PU until the communication is resumed on the next available channel. Handoff delay of a CR user comprises of

waiting time, spectrum sensing time, and channel switching time (Wang et al., 2011; Zhang, 2009). Increase in handoff delay can cause sufficient degradation in transmission of an SU. Therefore, a good handoff strategy should encounter a minimum handoff delay. The work proposed in (Dulaimi et al., 2016; Lertsinsrubtavee et al., 2014; Hernández et al., 2015; Yin et al., 2013; B. Wang et al., 2009; C.W. Wang et al., 2009; C.-W. Wang et al., 2009; Tran et al., 2015; Dahiya, 2014) address handoff delay in detail.

### A. Energy Efficiency

Energy efficiency is highly desirable in CRNs due to limited lifetime of battery resources. Energy efficiency can sufficiently extend the life of a network. In certain situations such as forests fire detection (Hefeeda and Bagheri, 2007), battle field communications (Murty, 2003), underground mines monitoring (Li and Liu, 2009), disaster management (George et al., 2010), smart grids (Khan et al., 2016), and high alert zones (Sharma et al., 2015), it is undesirable to replace the battery source of a CR device. The importance of energy becomes even more significant in situations where a user has to switch its on-going transmission to another vacant channel. This involves use of energy during the sensing process (before performing the handoff action). The authors of (Shokri et al., 2015, 2013; Usman et al., 2015; Vijayakumar et al., 2014; Chai et al., 2016; Pandya et al., 2015) focus on designing energy efficient spectrum handoff algorithms. In addition, the survey presented in (Xu et al., 2015) highlights important aspects on how to control the transmission power of CR users to save as much energy as possible.

### 5.4. QoS assurance

Some applications such as live streaming, video on-demand (VoD), and online gaming desire for strict QoS requirements in traditional wireless and CR networks, therefore the design of a good handoff strategy should account for these requirements. QoS in CRNs depends on many factors such as transmission rate, PU arrival rate, number of handoffs, handoff delay, waiting time, and probability of false alarm. The handoff schemes proposed in (Yin et al., 2013; Giupponi et al., 2008; Shankar, 2007; Dahiya, 2014; Wu et al., 2014) consider QoS as an essential part of their design process, however, most of these strategies suffer with the traditional limitations of not achieving maximum channel utilization and energy efficiency (Ahmad et al., 2015).

### 5.5. Throughput

Throughput is the total amount of data transferred by an SU in a specific time unit. In CRNs, it can be termed as the throughput achieved by an individual user or the overall throughput of the network. The works proposed in (Dulaimi et al., 2016; Lertsinsrubtavee et al., 2014; Hernández et al., 2015; Wang et al., 2012; Yi et al., 2014; Hu et al., 2007a; Wu et al., 2014) focus on maximizing throughput for secondary users, however, some of the aforementioned also suggest to increase the transmission power for an SU to achieve a maximum throughput value. This may result in harmful interference to the transmission of neighboring PUs. Moreover, number of handoffs affects the overall throughput for SUs since the SUs have to stop their transmission on PU arrival and look for other channels. In some situations, an SU has to remain idle for a long period of time unless the corresponding PU leaves the channel or an SU finds another vacant space to continue transmission. This waiting time results in serious decrement in an SU's throughput.

### 5.6. Total service time for secondary users

Total service time for an SU is the time it takes to complete the

**Table 5**  
Time triggered handoff schemes with their performance criteria.

Ref. #	Number of handoffs	Channel utilization	Delay/Handoff delay	Energy efficiency	QoS assurance	Throughput maximization	Total service time
(Dulaimi et al., 2016)	✓		✓			✓	✓
(Lertsinsruttavee et al., 2011)			✓		✓		
(Tian et al., 2014)	✓	✓					
(Zhu et al., 2007)						✓	✓
(Zakariya et al., 2015)							✓
(Lertsinsruttavee et al., 2016)	✓				✓	✓	
(Song et al., 2010)						✓	
(Wu et al., 2014)	✓				✓	✓	✓
(Wu et al., 2016b)		✓					
(Bicen et al., 2015)				✓			✓
(Min et al., 2011)		✓					✓
(Kahraman et al., 2015)	✓	✓	✓				
(Hernández et al., 2015)		✓	✓			✓	
(Pham and Chong, 2013)		✓					
(Pham et al., 2014)		✓					
(Wang et al., 2009a, 2009b, 2009c)	✓	✓					
(Wang et al., 2012)	✓						✓
(Wang et al., 2010)			✓				
(Yin et al., 2013)	✓		✓		✓		
(Wang et al., 2009a, 2009b, 2009c)	✓		✓				
(Shokri and Fischione, 2015)						✓	✓
(Willkomm et al., 2005)	✓					✓	
(Giupponi et al., 2008)		✓			✓		
(Wang et al., 2011)					✓		✓
(Tayel et al., 2016)							✓
(Mehrnoush et al., 2017)						✓	✓
(Oliaee et al., 2014)		✓					
(Tran et al., 2015)		✓	✓				
(Usman et al., 2015)						✓	
(Shankar, 2007)					✓	✓	✓
(Vijayakumar et al., 2014)	✓			✓			
(Yi et al., 2014)	✓					✓	✓
(Chai et al., 2016)				✓			
(Lertsinsruttavee et al., 2014)	✓		✓			✓	
(Dahiya, 2014)			✓		✓		
(Talat et al., 2016)							✓
(Lertsinsruttavee et al., 2010)			✓				
(Zahed et al., 2013)	✓						
(Mir and Munir, 2017)	✓	✓	✓			✓	✓
(Premarathne et al., 2017)		✓	✓				✓
(Hu et al., 2007a)	✓					✓	

transmission on an allocated channel. Total service time comprises of waiting time, sensing time, channel processing time, and transmission time. The approaches presented in (Wang et al., 2012; Zakariya et al., 2015) consider waiting time to be an important factor affecting the service time of SUs. Likewise, waiting time reduction is shown in the results presented in Shankar (2007), Yi et al. (2014). The authors of Dulaimi et al. (2016), Tayel et al. (2016), Min et al. (2011), Shokri and Fischione (2015), Giupponi et al. (2008), Yi et al. (2014), Wu et al. (2014) also focus on increasing service time of SUs without degrading the performance of PUs.

To provide a more comprehensive analysis we summarize all the time triggered strategies with their performance criteria in Table 5.

**6. Challenges, issues and future directions for a time triggered handoff process**

In this section, we discuss the challenges and issues related to a time triggered handoff process and outline the future research directions and opportunities. Without the loss of generality, these issues are equally important for all sorts of handoff schemes.

*6.1. Intelligent handoff process*

Most of the existing time triggered handoff schemes lack the

spectrum learning feature in their design (Christian et al., 2012). Ideally, an SU should know the traffic patterns of a PU via its sensing capabilities and adapt to most suitable handoff technique wherever needed. As soon as the traffic patterns of a PU change, the SU should notice that and choose between, a proactive or a reactive handoff decision, accordingly. Despite the fact that various schemes consider sensing as an important factor in their design, still this issue requires further in depth investigation. In addition, device's energy factor should be kept in consideration while designing a learning-based sensing/handoff strategy. We recommend researchers to go through an important work presented in Zhu et al. (2017). Though, this intelligent handoff scheme is designed for virtual wireless networks (addressing a specific train communication scenario), it can easily be adjusted within the context of a CRN.

*6.2. Priority based spectrum handoff*

In case of an emergency, such as natural or man-made disasters and health care emergencies or accidents, and security related situations, the spectrum of a PU can opportunistically be used by an SU in order to provide communication (Maldonado et al., 2005; Rathee et al., 2016). These emergency conditions require channel selection and handoff to be performed rather quickly compared to normal situations. Thus, a patient in an ambulance would desire for a priority e-health

services with better mobility and QoS support compared to another person sitting at home trying to utilize bandwidth for his or her routine stuff. Therefore, spectrum handoff schemes should be designed by keeping in mind the fast varying nature of modern day applications.

### 6.3. Interference avoidance

Primary users are the licensed owners of spectrum whereas the SUs have opportunistic access to the spectrum. The simultaneous appearance of an SU on a licensed spectrum band can cause harmful interference to a PU. This is a major issue in CRNs. The interference to the PU's transmission should be avoided during the occurrence of handoff. For an accurate and efficient handoff process, the interference avoidance mechanism should be proposed in design process of a handoff strategy (Kumar et al., 2016). Moreover, to further mitigate the effects of users' interferences, next channel selection and handoff should be performed with minimal delay. This requires a suitable organization of an SU's traffic in real time (Kumar et al., 2015). Some recent researchers also suggest that it is rather useful to consider the interference between users as an important resource especially when traditional wireless and CR users coexist. Interested readers may refer to a promising recent work presented in (Zhang et al., 2017).

### 6.4. Optimization of parameters involved in handoff decision

It is difficult and time consuming to consider the impact of all the parameters (such as throughput, number of handoff, etc.) in designing a handoff strategy due to the architectural complexity constraints. Therefore, parameters should be prioritized according to the situation. For example, in an ad-hoc scenario, special attention should be given to the random movements of SUs and PUs which may seriously affect the handoff process. In some other static situations, utility or throughput maximization could be prioritized since the users movements are not random and can be ignored in the design process. Thus, "dynamic adjustment/mining" of all important parameters is an important current and future challenge (Xingya et al., 2016).

## 7. Conclusion

In this paper, spectrum handoff approaches based on time triggering are summarized. Various existing schemes are classified in non-proactive, reactive, and hybrid/adaptive handoff categories and their pros and cons are discussed in detail. Several figures and tables are provided to analyze time triggered handoff approaches in a comparative manner. We also discussed several important parameters such as throughput, delay, number of handoffs, and various others which are important in designing a handoff strategy. In future, we will continue to present any further research and advancement related to cognitive radio networks.

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